

EASY-ROB[™] Collision

Collision Detection of 3D Objects

The high-performance EASY-ROB[™] Collision is used for integration into technology-based software applications. Quickly and accurately check your 3D application for collisions-

It doesn't matter how big your models are, you can rely on EASY-ROB™ Collision!



Various Calculation Methods

- Collision Detection
- Clearance
- Distance



Hierarchical Representation

 Intelligent and fast with OBBTree-Tight-Fitting



Threadsafe

 Parallel collision test safe on multi-core CPU



API

 C/C++ and C# Method class
ERK_CAPI



Mathematics

 Method class for math. calculations, e.g. of homogeneous matrices



- Including various calculation methods
- High performance with low hardware requirements
- Thread safe
- Easy integration into technologydriven software solutions
- Available for Windows® 64-Bit



EASY-ROB™ Collision

Collision Detection of 3D Objects

More than 1000 times in use -

Now finally free available! Thanks to the open software architecture EROSA, EASY-ROB[™] Collision is now available.



Collision Detection

- Method of whether two triangulated models collide
- Collision detection according to the first colliding triangle pair
- Calculation of all colliding triangle pairs

Application Possibilities

- Animation and simulation
- Motion planning
- Assembly tests
- Offline programming
- Measurement protocols
- Virtual Prototyping
- Surgical simulation
- Haptic rendering
- Molecular design
- Industry-independent



Clearance

 Checks if two models are closer or further than a defined tolerance distance



Distance

- Calculates the smallest Euclidean distance between two non colliding models and
- The 2 closest points on the models

System requirements

Windows® 7/ 8/ 10, 64-Bit

Support

Support for individual integration

Integration

- Detailed doxygen documentation
- Programming examples for MS Visual Studio® C/C++ und C#

More modules available:

- EASY-ROB[™] VISU
- EASY-ROB[™] 3D-PDF Export
- EASY-ROB[™] RobLibs